

Stability defined precisely

Lyapunov stability

Premise: Consider the ordinary differential equation

$$\dot{x} = f(x), \quad x \in \mathbb{R}^n \quad (\text{ODE with } n \text{ scalar state variables})$$

f is a continuous function.

x^* is an equilibrium point, so that $f(x^*) = 0$.

Definition: Lyapunov stability

x^* is Lyapunov stable if, for every $\epsilon > 0$, there exists a $\delta > 0$ such that if $\|x(0) - x^*\| < \delta$,

then for all $t \geq 0$, we have $\|x(t) - x^*\| < \epsilon$.

What does this mean?

$$\rightarrow \|x(0) - x^*\| < \delta$$

means

the initial condition $x(0)$ is within a distance δ of the equilibrium point x^* .

$$\rightarrow \|x(t) - x^*\| < \epsilon \quad \text{for all } t \geq 0$$

means

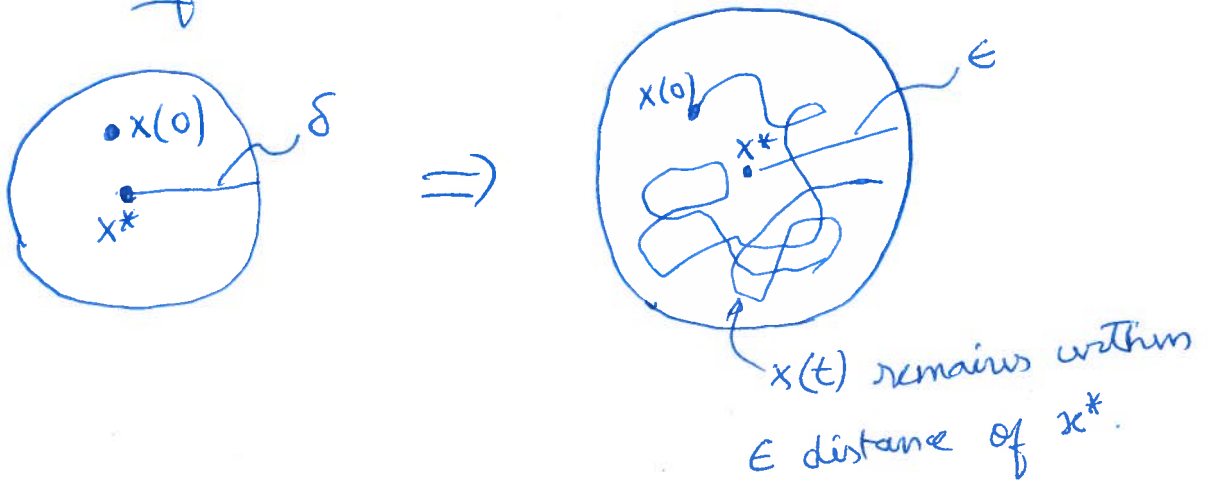
the $x(t)$ is within a distance ϵ of the equilibrium point x^* for all time.

Lyapunov stable if

Someone picks an ϵ

and you can ^{always} pick a corresponding δ

so that if the initial condition is within δ of x^* .



More informally,

you can always start close enough to x^* (within distance $\delta > 0$) so that the trajectory $x(t)$ always remains close to x^* (within whatever distance $\epsilon > 0$).

Examples

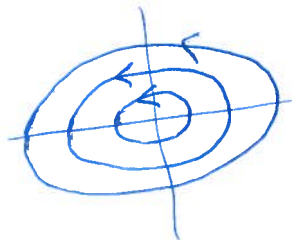
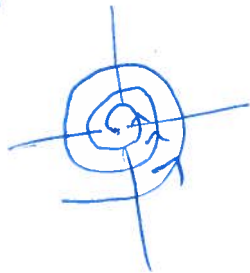
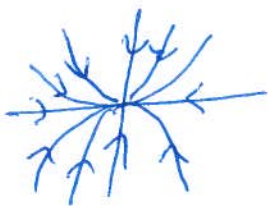
(1) All eigenvalues of the Jacobian of $f(x)$ at x^* have negative real parts. $\lambda_1, \dots, \lambda_n$

\Rightarrow Lyapunov stable.

(2) in 2D ($x \in \mathbb{R}^2$) linear systems.

stable spiral, stable node, center

all Lyapunov stable.



~~At~~ If even one eigenvalue of Jacobian of $f(x)$ at x^* has a positive real part \Rightarrow not Lyapunov stable.
(Lyapunov unstable)

If some eigenvalues of Jacobian have negative real parts and some have zero real parts, the eq. point x^* can be either Lyapunov stable or unstable.

Need to do a nonlinear analysis to determine stability.

Asymptotically stable fixed point


Definition. x^* is asymptotically stable if it is Lyapunov stable and there exists a $\delta > 0$ such that if $\|x(0) - x^*\| < \delta$, then

$$\lim_{t \rightarrow \infty} \|x(t) - x^*\| = 0$$

More informally, $x(t) \rightarrow x^*$ as $t \rightarrow \infty$. ~~and does not~~
if you start close enough to x^* .

Examples

- (1) All eigenvalues of Jacobian of $f(x)$ at x^* have negative real parts
 $\Rightarrow x^*$ is asymptotically stable.

- (2) center  is Lyapunov stable
but NOT asymptotically stable

- (3) finite time stability is a special case of asymptotically stable. if $x(t) \rightarrow x^*$ in finite

time, it is also true that $x(t) \rightarrow x^*$ as $t \rightarrow \infty$.

Exponential stability

x^* is exponentially stable if it is asymptotically stable and there exists α, β, δ such that

if $\|x(0) - x^*\| < \delta$, then

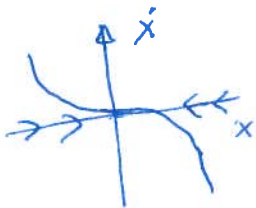
$$\|x(t) - x^*\| \leq \alpha \|x(0) - x^*\| e^{-\beta t} \quad \text{for all } t \geq 0$$

↖ This just bounds the rate of approach as at least as fast as an exponential decay.

Examples

(1) If all eigenvalues of the Jacobian of $f(x)$ at x^* have negative real parts
 \Rightarrow exponentially stable.

(2) $\dot{x} = -x^3$ $x^* = 0$



is Lyapunov stable,
asymptotically stable

But NOT exponentially stable.
(approach to x^* is slower than exponential).

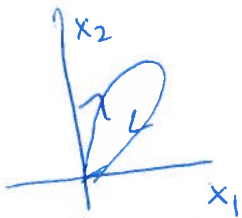
Further remarks.

(1) exponentially stable \Rightarrow asymptotically stable \Rightarrow Lyapunov stable.

(2) There are weird examples which have the property that $x(t) \rightarrow x^*$ as $t \rightarrow \infty$ but not Lyapunov stable. eg. Hahn's example. (1967) book pg. 191

$$\dot{x}_1 = \frac{x_1^2(x_2 - x_1) + x_2^5}{(x_1^2 + x_2^2)(1 + (x_1^2 + x_2^2)^2)} \quad \& \quad \dot{x}_2 = \frac{x_2^2(x_2 - 2x_1)}{(x_1^2 + x_2^2)[1 + (x_1^2 + x_2^2)^2]}$$

(originally due to Vinograd).



origin is a fixed pt. & attractive.

But there's a loop that starts & ends at 0. \Rightarrow not Lyapunov stable.

because we cannot find a δ for every ϵ .

even though there is a neighborhood around 0 such that if you start from there $x(t) \rightarrow 0$ as $t \rightarrow \infty$.

(Such loops that start and end at a fixed point are called homoclinic orbits).